

In our approach we iteratively refine the upperlevel basis functions BF_k to a set of diakoptic basis functions. The k -th diakoptic basis function can be found by exciting the k -th lowerlevel port LP_k while leaving the other lowerlevel ports LP_1 open (unexcited). It can be proven that the overall solution based on these basis functions will match the full solution—i.e. the solution from one direct MOM—exactly (apart from numerical inaccuracies). Therefore we iteratively construct the profiles resulting from exciting each of the lowerlevel ports separately. Thus the original sub-sectional upperlevel “roof-top” basis functions are extended into full-domain diakoptic basis functions.

Our iterative method is based on Modified Diakoptics (MD) [5] and has a physical interpretation (Fig. 2). During the lowerlevel MOM simulation no metallization other than that of the subcircuits connected to the considered artificial port is taken into account (Fig. 2a). The currents on each of these subcircuits will excite currents on all the other subcircuits by (1st order) field coupling (Fig. 2b). During the first iteration these 1st order coupling currents are calculated. These currents will, in turn, excite (2nd order) coupling currents on all the other subcircuits (Fig. 2c). These are calculated in the second iteration. These currents will again excite currents on all the other subcircuits and so forth. The actual current is the sum of the lowerlevel MOM current and the currents from the different iterations (Fig. 2d).

In order to simplify the notation we combine the sides in the complete circuit into blocks of sides: all the sides belonging to the same subcircuit s (excluding the portsides of the connected lowerlevel ports) are combined into one block for each subcircuit (I_{sk}^S); all the portsides belonging to the same lowerlevel port LP_1 are also combined into one block for each lowerlevel port (I_{lk}^P). The coupling between these blocks of sides are combined into the Z -matrices Z_{st}^S , Z_{sl}^{SP} and Z_{lm}^P , describing the coupling between the sides of subcircuits (s) and (t) and of lowerlevel ports LP_1 and LP_m .

Using the iterative correction $I_{sk}^S(n) = I_{sk}^S(n-1) + \Delta I_{sk}^S(n)$ and omitting the coupling between the highest order coupling currents, the block iteration formulas for basis function BF_k become:

$$\Delta I_{sk}^S(n) = \begin{cases} 0 & \text{if } s = t_{1,2} \\ -(Z_{ss}^S)^{-1} [Z_{sk}^{SP} I_{lk}^P + Z_{st_1}^S I_{t_1 k}^S + Z_{st_2}^S I_{t_2 k}^S] & \text{if } s \neq t_{1,2} \end{cases}$$

$$\Delta I_{sk}^S(n) = -(Z_{ss}^S)^{-1} \left[\sum_{\substack{t=1 \\ t \neq k}}^S Z_{st}^S \Delta I_{tk}^S(n-1) \right]$$

with $t_{1,2}$ the subcircuits connected to lowerlevel port LP_k .

In the Modified Diakoptics technique, the results of each step in the iteration are updated into the overall currents but after the complete iteration, just as in the standard Block Jacobi linear iterative technique. The convergence can be accelerated by updating the results of each step immediately,

resulting in Block Gauss-Seidel (BGS) [6]. The iteration formula then becomes:

$$I_{sk}^S(n) = -(Z_{ss}^S)^{-1}.$$

$$\left[Z_{sk}^{SP} I_{lk}^P + \sum_{t=1}^{s-1} Z_{st}^S I_{tk}^S(n) + \sum_{t=s+1}^S Z_{st}^S I_{tk}^S(n-1) \right]$$

IV. NUMERICAL EXAMPLE.

We applied our technique to the simulation of a lowpass filter (Fig. 3) consisting of an input section with a folded matching stub, a step in width, a central section with three spiral inductors and two patch capacitors, another step in width and finally an output section with a folded matching stub.

This circuit was gridded without and with an edge mesh yielding resp. 349 and 825 unknown variables, divided into 9, 12 and 19 (Fig. 3) parts, and simulated from 1 GHz to 4 GHz. The reference situation was obtained by simulating the complete circuit as a whole (“full”).

The convergence of the S_{11} -parameter over the complete frequency range for BGS ($n = 349$) is illustrated in Fig. 4. Similar results are obtained for S_{12} (S_{21}) and S_{22} .

Our iterative technique reduces the solution time to 65% for $n = 349$ and 25% for $n = 825$ for an accuracy of -80 dB in the S -parameters. The solution time will decrease more substantially as the number of unknowns further increases.

We tested our approach to other examples such as transmission lines, double stub filters and bandpass filters with very similar results as for the lowpass filter.

REFERENCES

- [1] R.F. Harrington, *Field Computations by Moment Methods*, Macmillan, New York, 1968.
- [2] Jeannick Sercu, Niels Faché, Frank Libbrecht, and Paul Lagasse, “Mixed potential integral equation technique for hybrid microstrip-slotline multilayered circuits using a mixed rectangular-triangular mesh,” *IEEE Trans. Microwave Theory Tech.*, vol. MTT-43, no. 5, pp. 1162–1172, May 1995.
- [3] Khahil Kalbasi and Kenneth R. Demarest, “A multilevel formulation of the method of moments,” *IEEE Trans. Antennas Propagat.*, vol. 41, no. 5, pp. 589–599, May 1993.
- [4] Chalmers M. Butler, “Diakoptic theory and the moment method,” in *IEEE AP-S Int. Symp. Digest*, Dallas, USA, May 8–10 1990, IEEE, vol. I, pp. 72–75.
- [5] Felix Schwering, Narinda Nath Puri, and Chalmers M. Butler, “Modified diakoptic theory of antennas,” *IEEE Trans. Antennas Propagat.*, vol. 34, no. 11, pp. 1273–1281, Nov. 1986.
- [6] R. Van Norton, “The solution of linear equations by the Gauss-Seidel method,” in *Mathematical Methods for Digital Computers*, Ralson and Wilf, Eds., chapter 3, pp. 56–61. John Wiley Sons Inc., 10th edition, 1967.

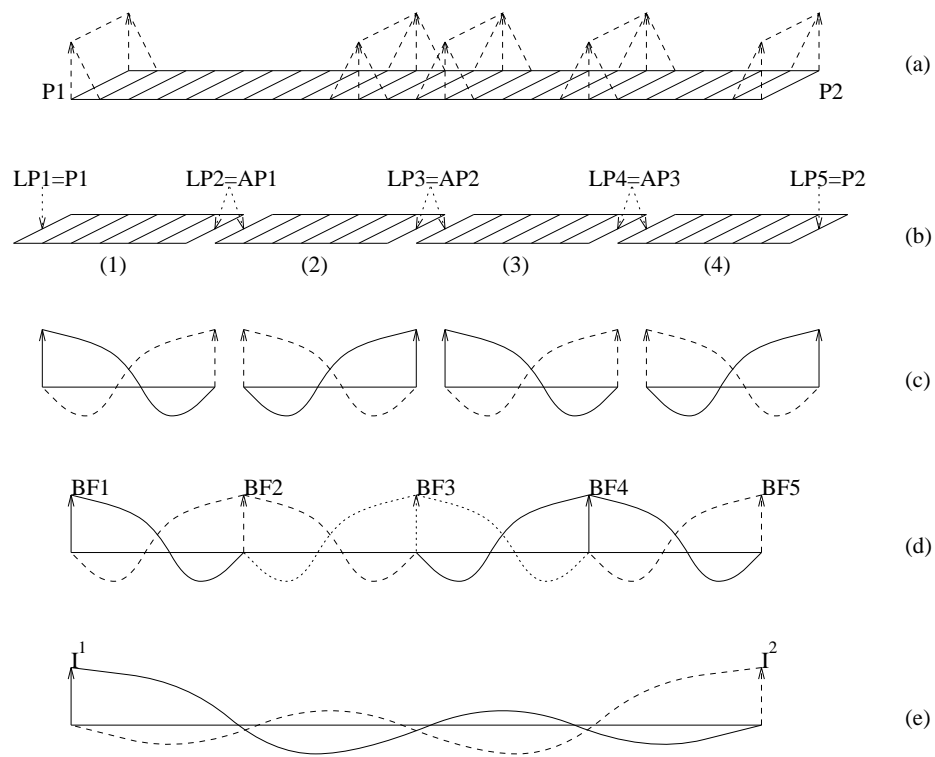


Fig. 1. Two-level Moments Method.

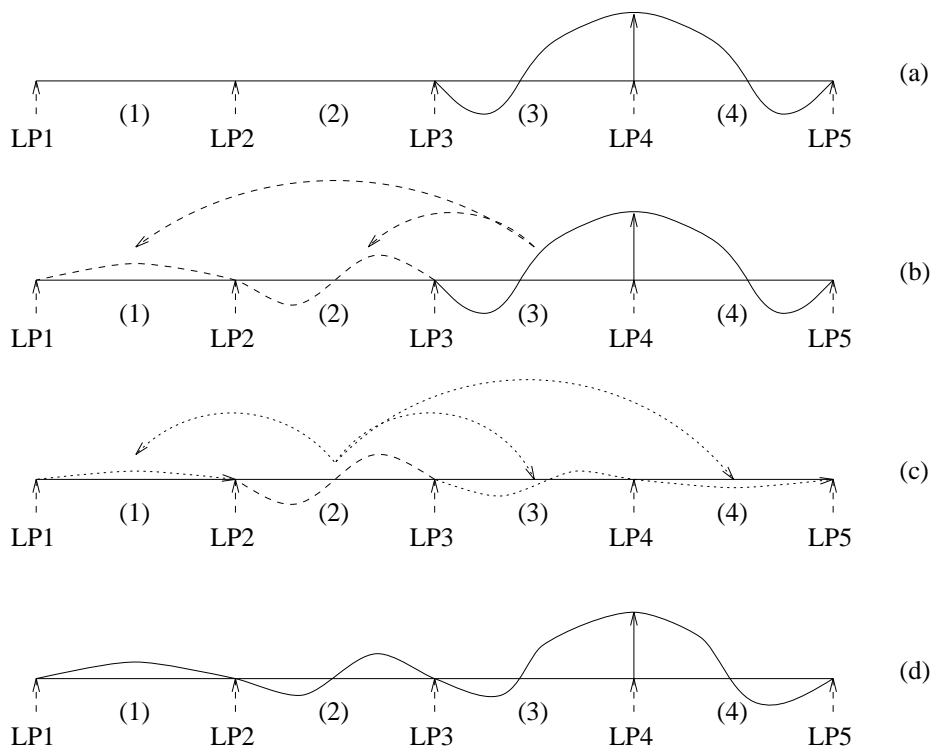


Fig. 2. Modified Diakoptics.

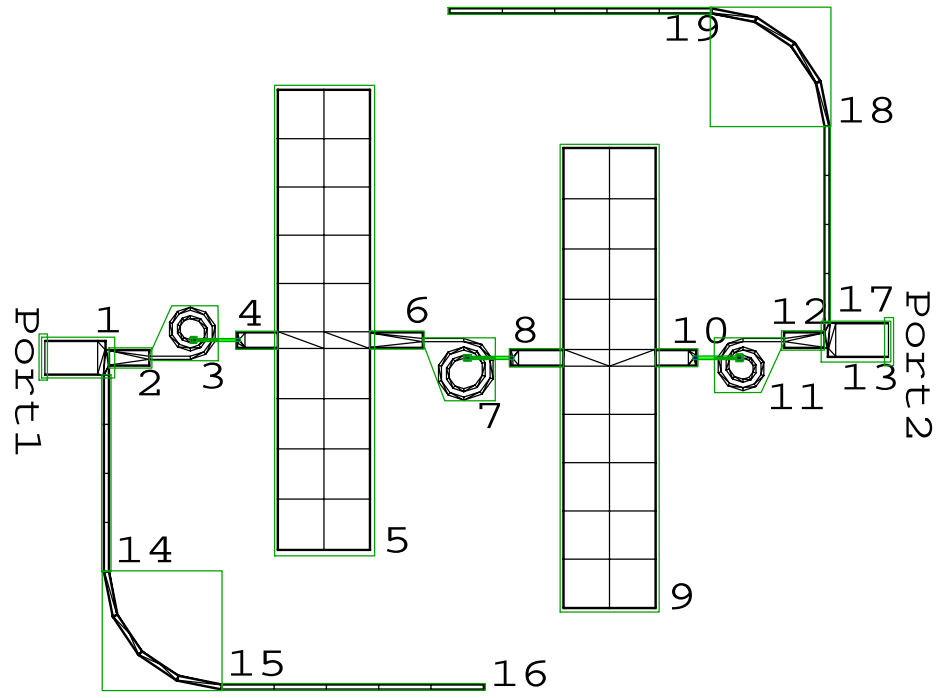


Fig. 3. Lowpass filter with 19 divisions.

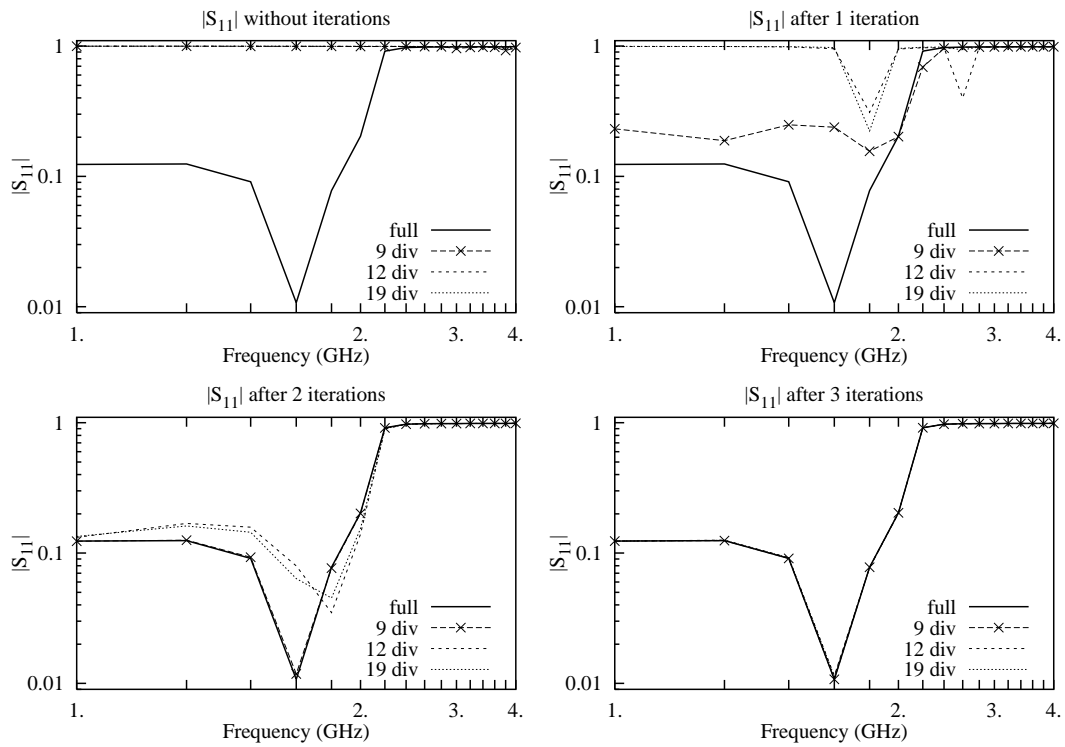


Fig. 4. Convergence of the reflection S-parameter (S_{11}) of the lowpass filter.